OpenDA-OpenMI framework for Hydrological data assimilation

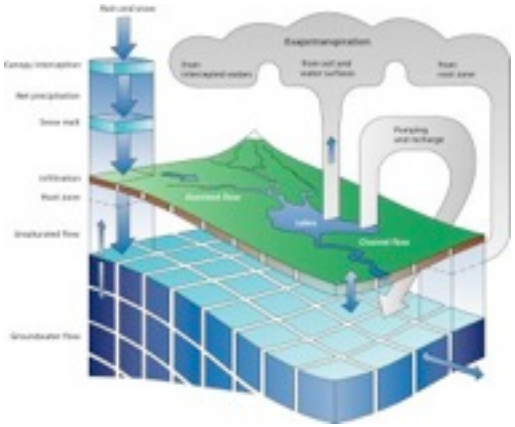
Nils van Velzen (TU-Delft)
Marc Ridler (DHI)

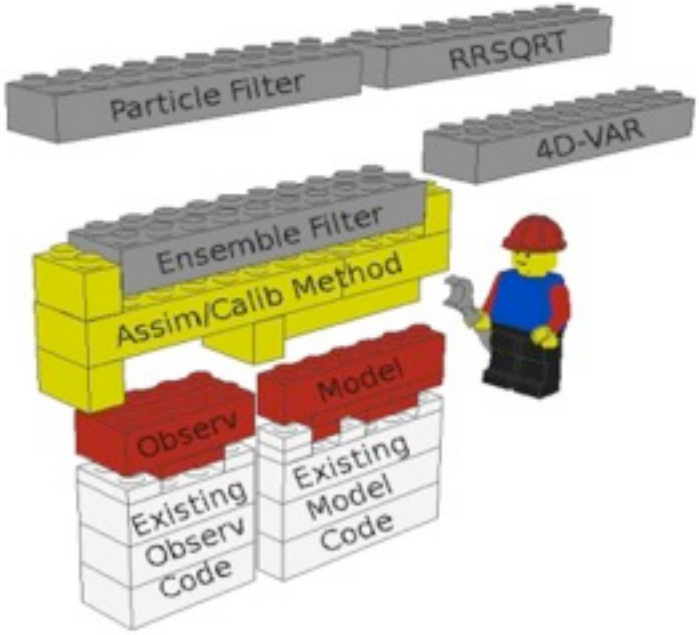
Overview

- Goal
- Black box coupling in OpenDA
- OpenMI
- OpenDA-OpenMI framework
- Problems
- Medium size example
- Next Steps

Goal

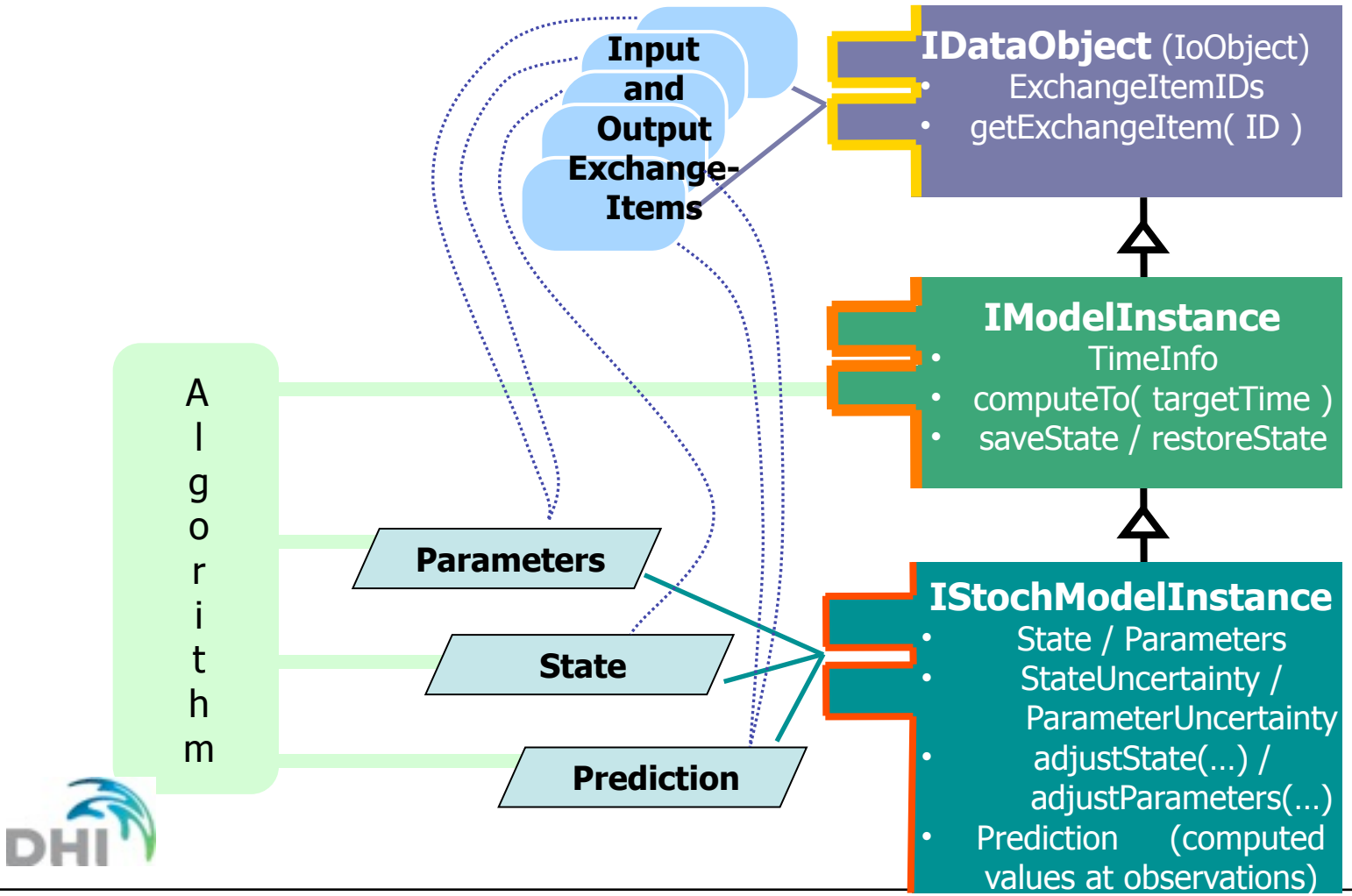
- OpenDA: framework for Data Assimiation
- MIKE-SHE: Integrated catchment modelling
- Data assimiltion with MIKE-SHE



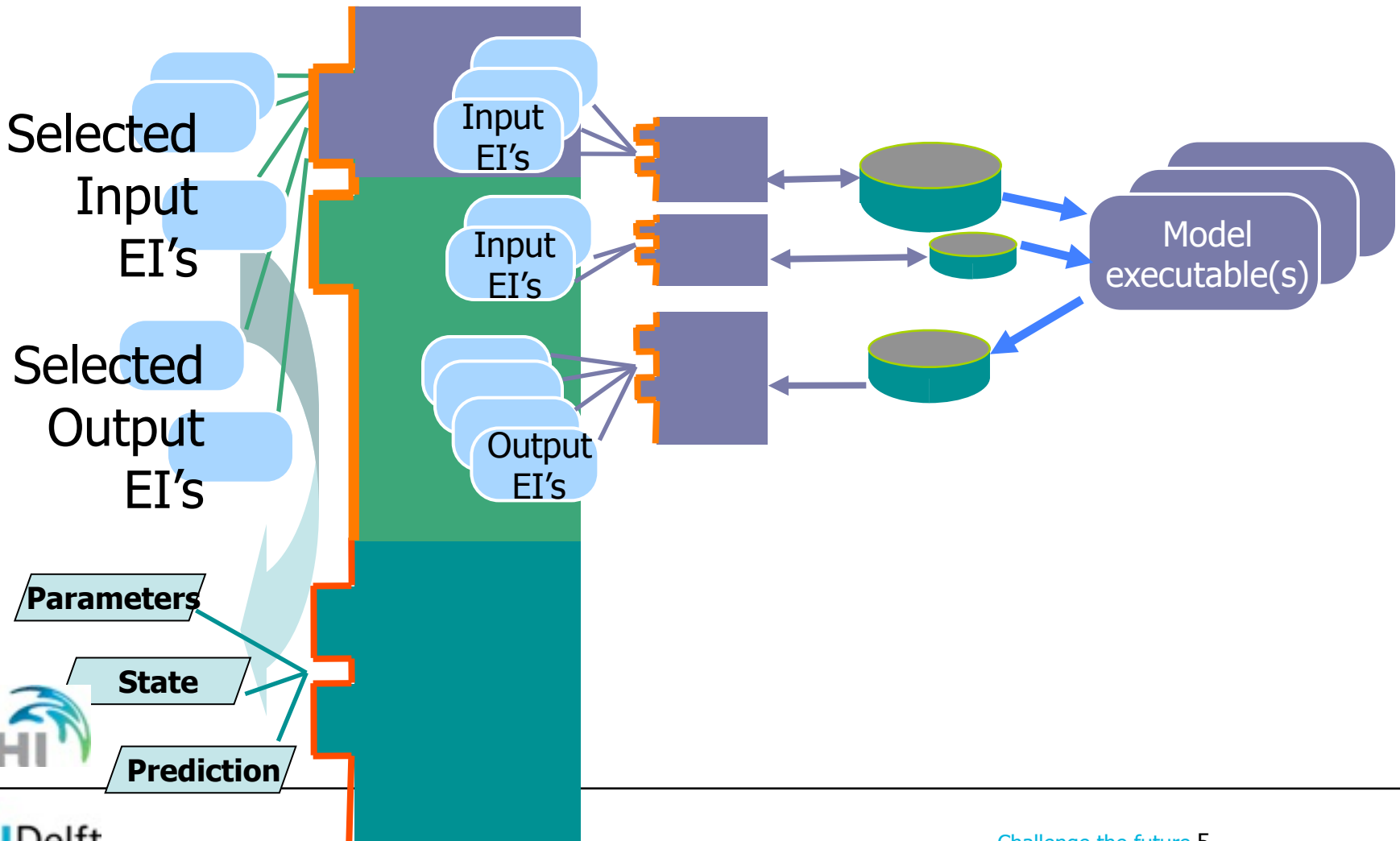


DHI

Black box coupling in OpenDA

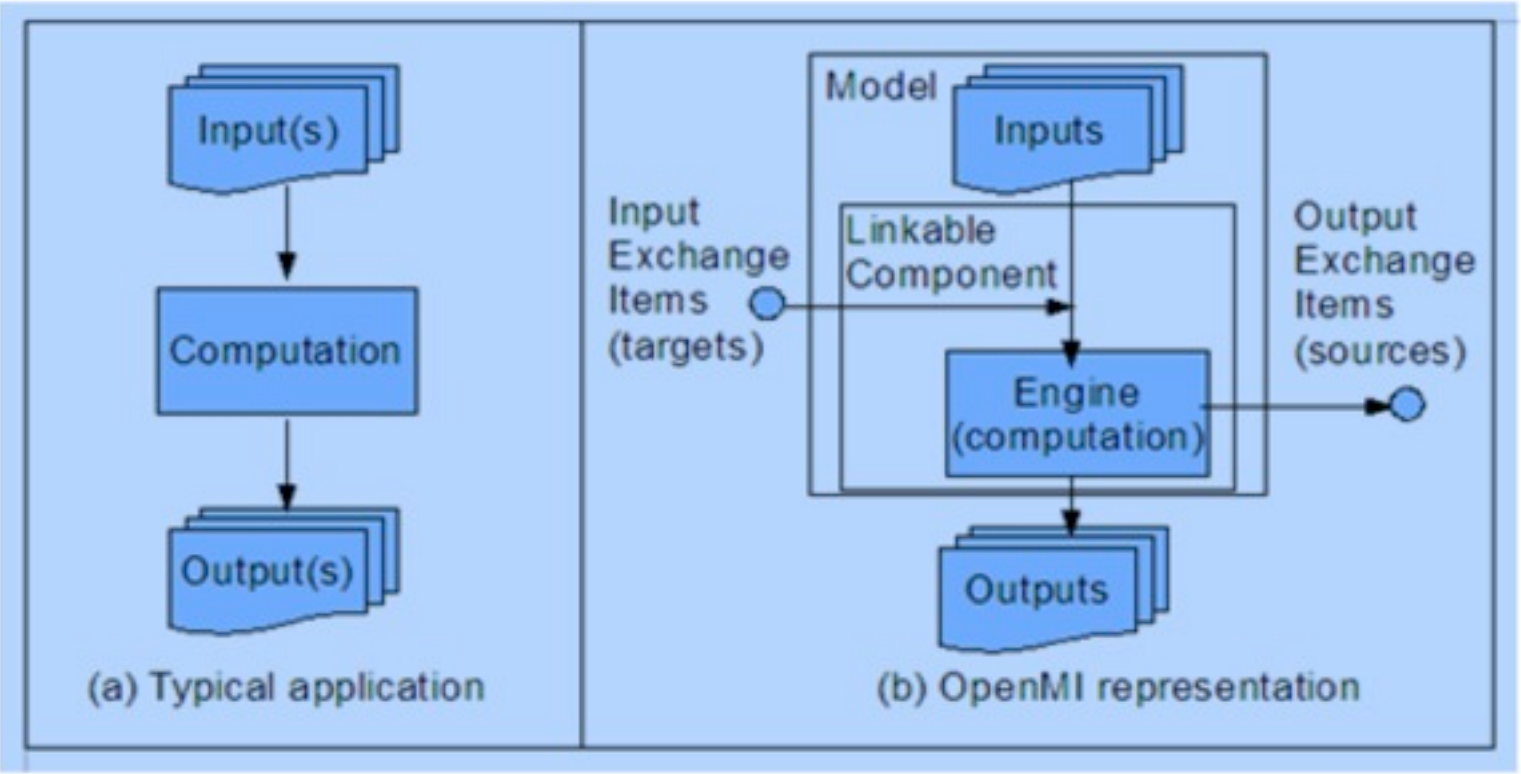


Black box coupling in OpenDA

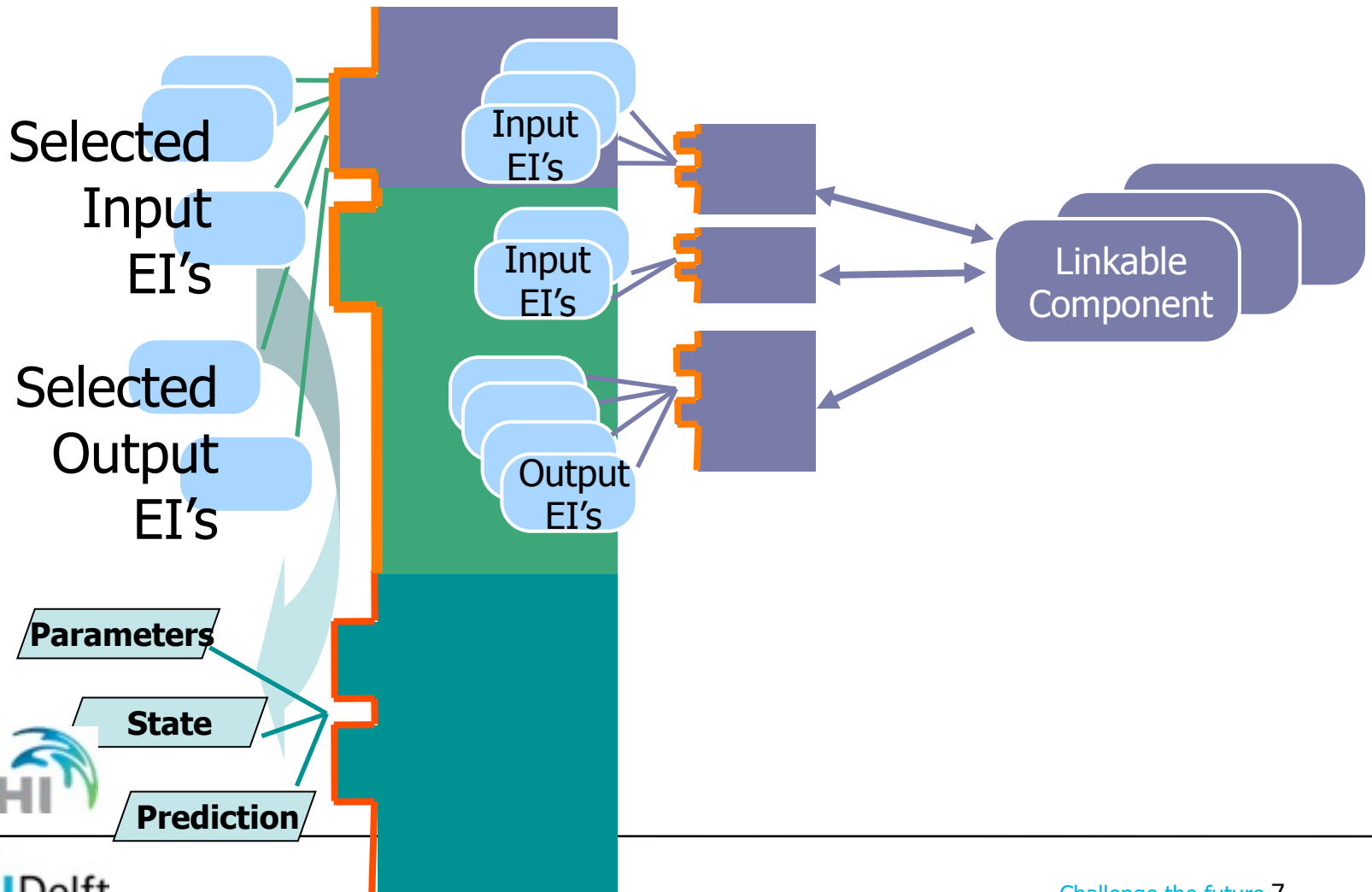


OpenMI

- MIKE-SHE has an OpenMI interface

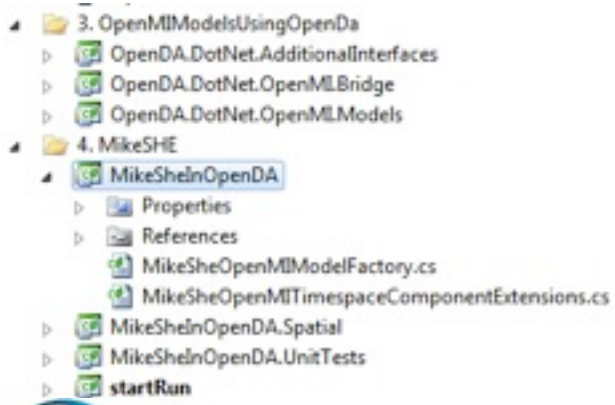


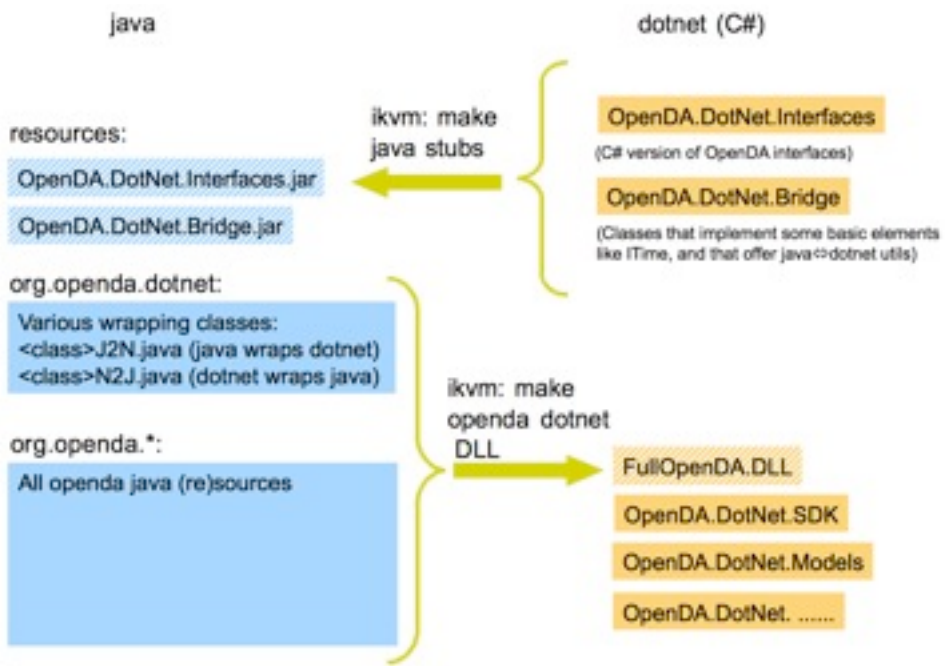
OpenDA-OpenMI framework



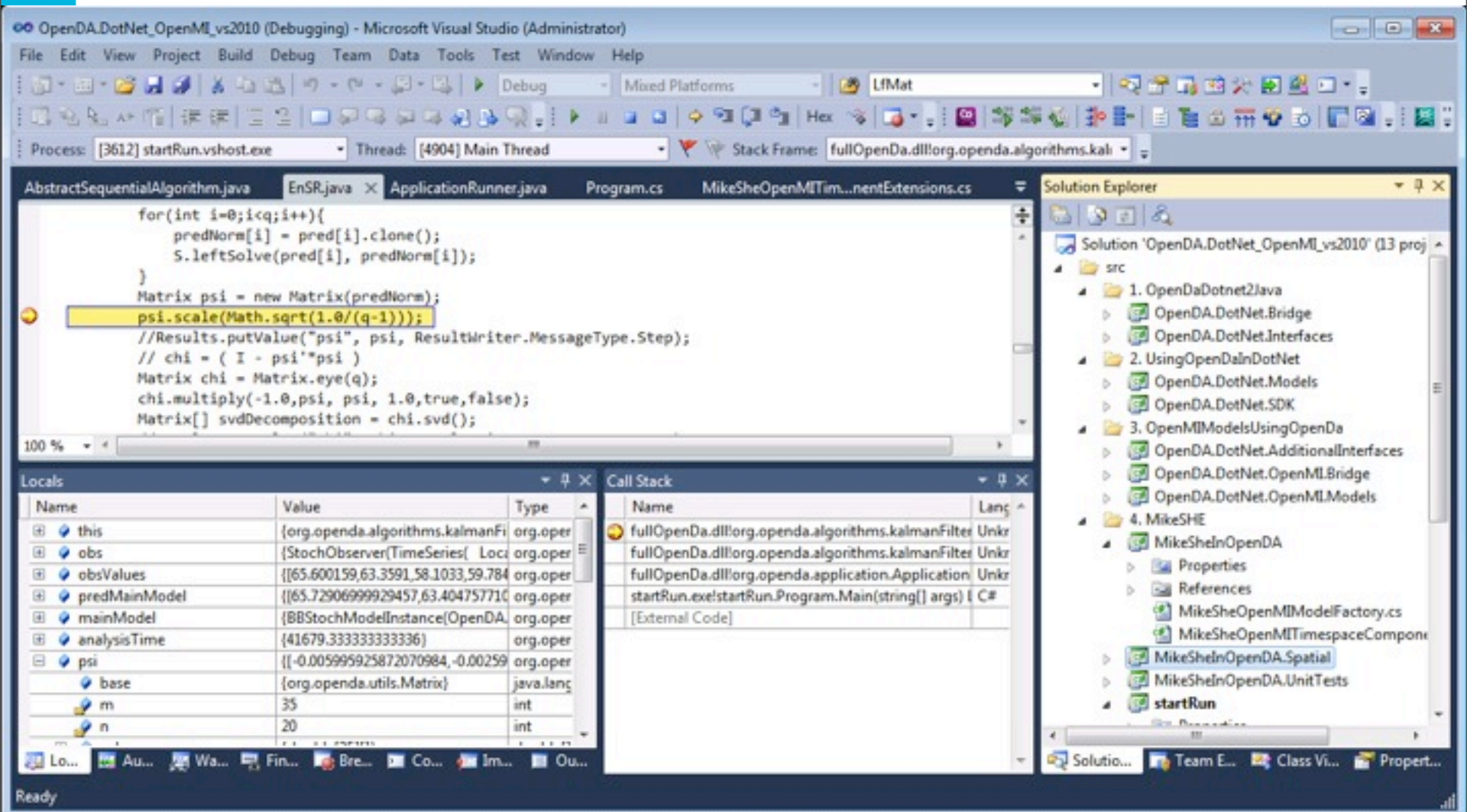
OpenDA-OpenMI framework

- Programming language :OpenDA (Java) OpenMI (C#)
- IKVM automatic translation of OpenDA to C# libraries
- Generic Layer
- MIKE-SHE specific Layer
- Debugging?





OpenDA-OpenMI framework



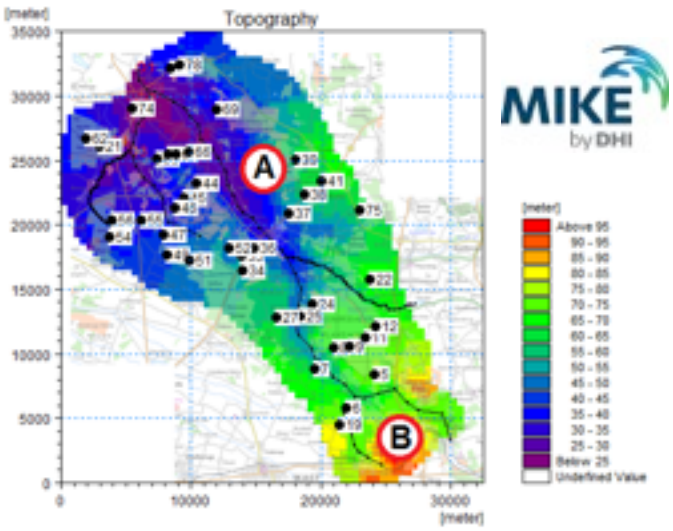
OpenDA-OpenMI framework

- One week behind a single desk in Delft
- Email/Skype
- Repository

Problems (found and fixed)

- SetExchangeItem (MIKE-SHE) not correctly implemented
  - Work around in OpenMI wrapper code
- Performance when all OpenMI exchangeItems are available
  - Configure MIKE-SHE to only export relevant/used ones
- Localization support in OpenDA Black Box is not optimal
  - Added optional interfaces for easy connection
- Observation matching in OpenDA Black Box only on exchangeItem ID
  - Added optional interfaces for full control

Medium size example



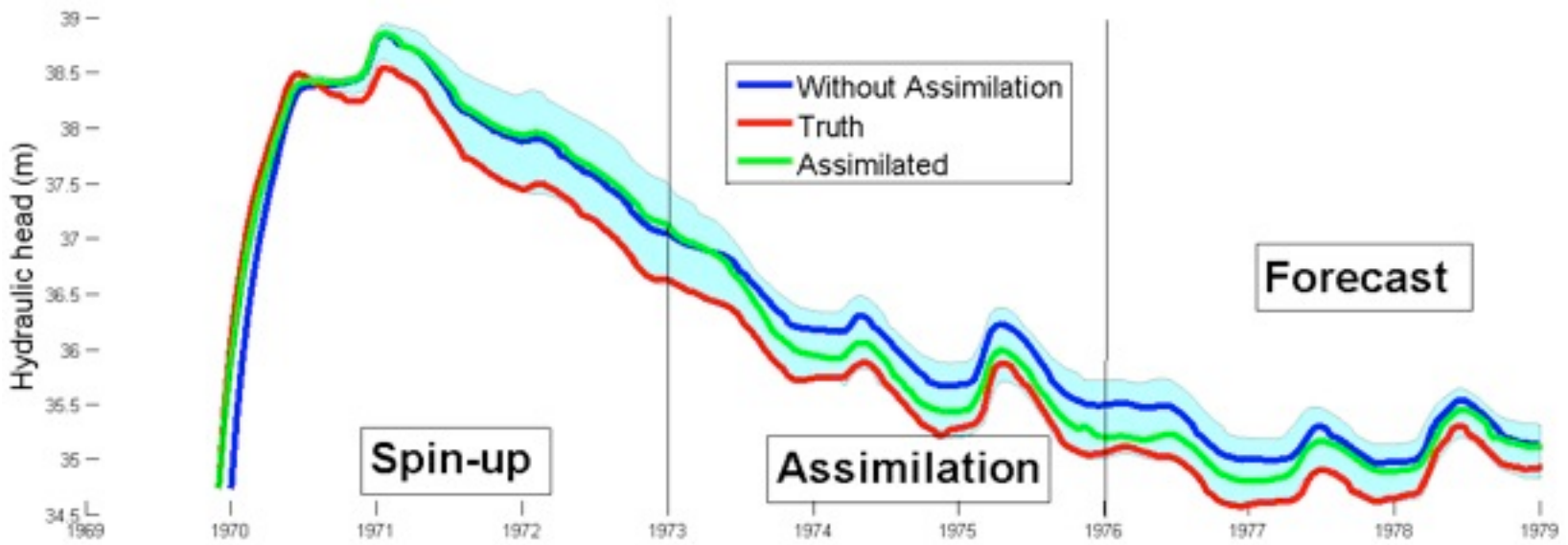
Karup Catchment

- Uncertainty based on GLUE (generalised likelihood uncertainty estimation)
- Perturbed
- Rainfall & Potential ET.
- Parameters (UZ, SZ, OL)

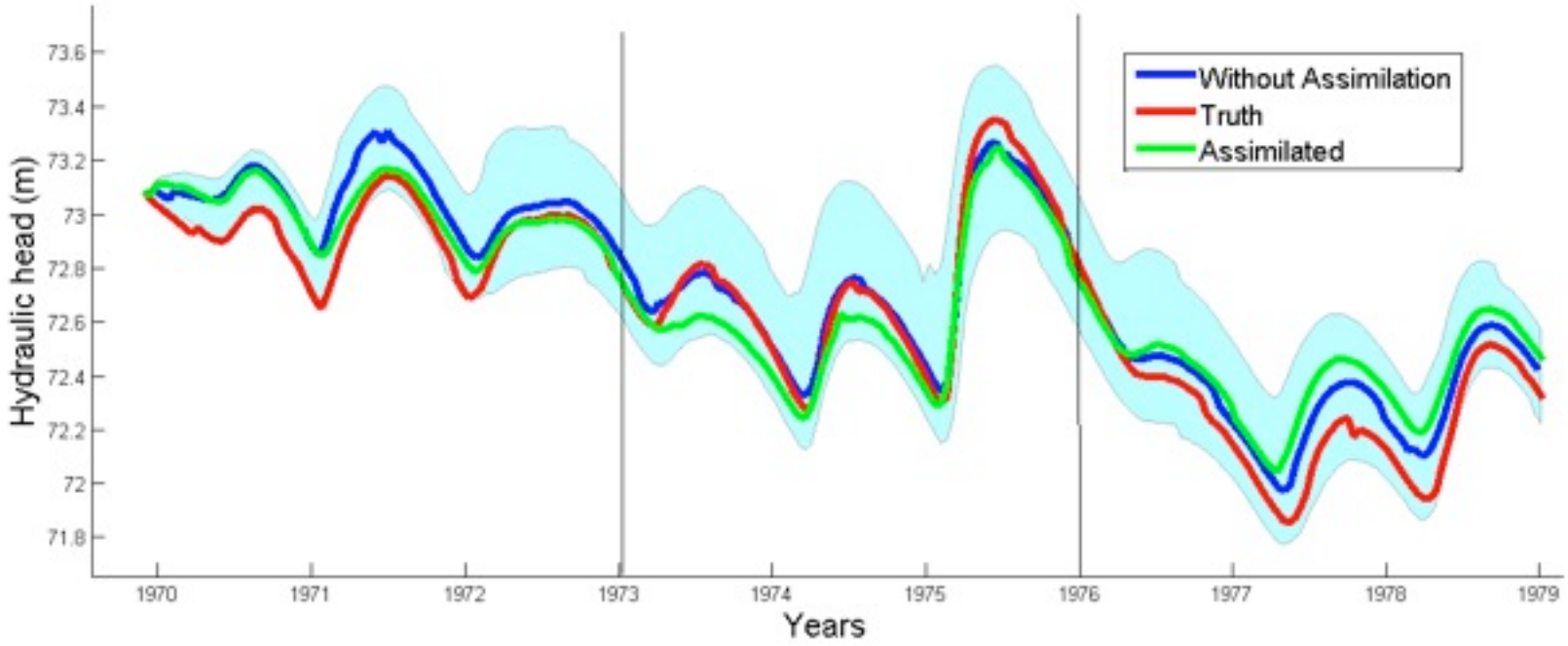
Ensemble Kalman filter

- 30 Ensemble members
- Daily hydraulic head observations (m = 35). Synthetic
- State updating (n = 522)
- Localization

At Point A


Hydraulic head (m)
39
38.5
38
37.5
37
36.5
36
35.5
35
34.5
1969
1970
1971
1972
1973
1974
1975
1976
1977
1978
1979
Without Assimilation
Truth
Assimilated
Spin-up
Assimilation
Forecast

At Point B


Without Assimilation
Truth
Assimilated
Hydraulic head (m)
73.6
73.4
73.2
73
72.8
72.6
72.4
72.2
72
71.8
1970
1971
1972
1973
1974
1975
1976
1977
1978
1979
Years

Next steps

- Doing all kinds of experiments
  - EnKF
  - EnSR
  - Localization
  - Various fields in model state
- DHI C# observation code
- …